

Lockheed Martin Low-Cost F-35 Simulator

Senior Design Team 514



Francisco Lopez

Meet the Team



Jonah Gibbons
*Manufacturing &
Electrical Engineer*



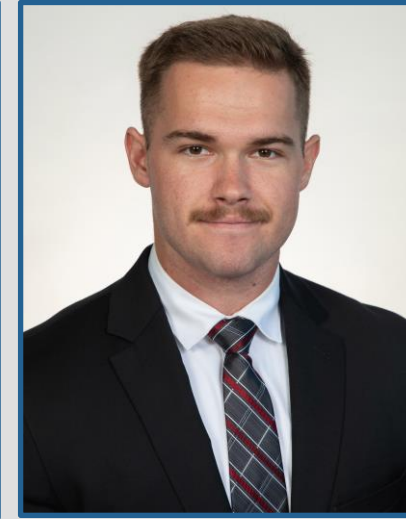
Laiken Kinsey
Project Manager



Francisco Lopez
*Control Systems
Engineer*



Branden Pacer
*Mechanical
Engineer & Web Design*



Will Rickles
*Mechatronics
Engineer*



Emelia Rodriguez
*Purchasing and
Research Engineer*

Francisco Lopez



Sponsor and Advisor



Andrew Filiault
Mechanical Engineer, B.S.
JSF F-35 Pilot Training and
Training Infrastructure Systems



FAMU-FSU
College of Engineering



Brandon Krick
Mechanical Engineer, Ph.D.
Associate Professor

Francisco Lopez



Project Objective



The objective of this project is to create F-35 flight controls that integrate with Lockheed Martin's simulator software to be used in the pilot training program.

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3D Printed Cockpit and Desktop Simulator

- ✈️ Pilots train in simulators to develop muscle memory and learn the unique operating procedures of the aircraft



Prepar3D with 3D Printed Cockpit



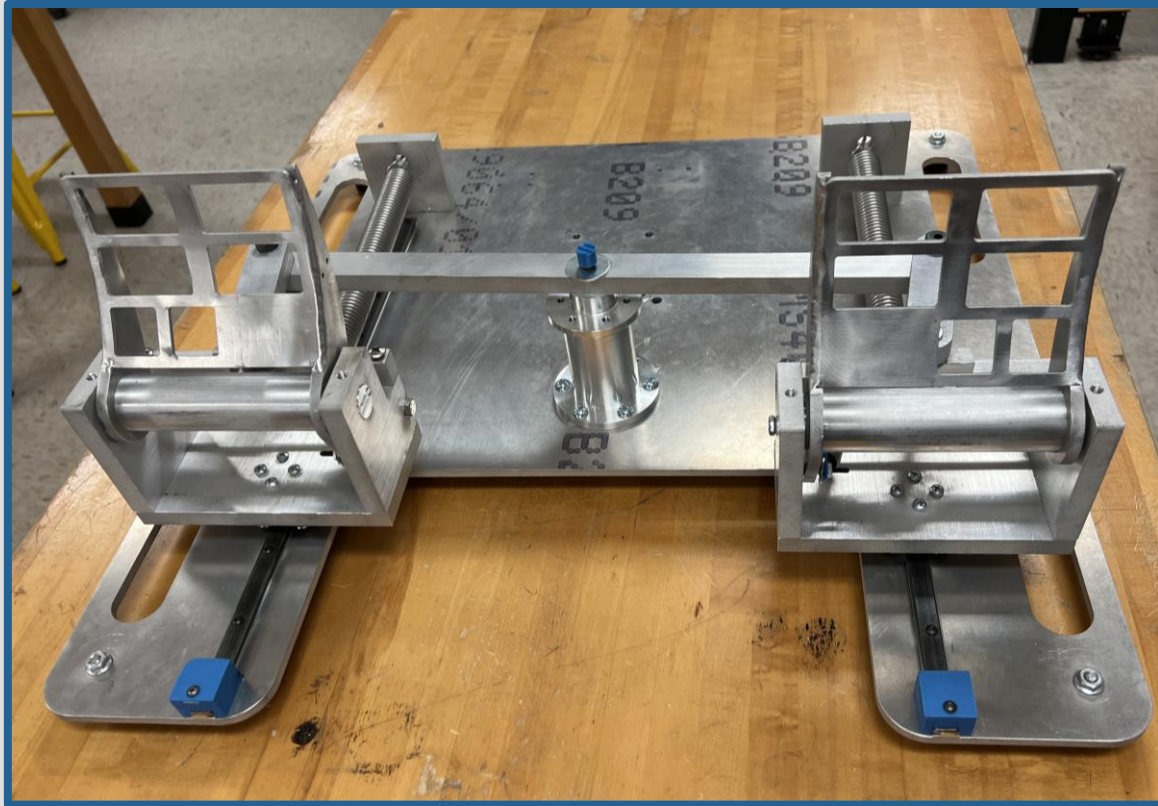
3D Printed Cockpit



Desktop Simulator

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Rudder Pedal System

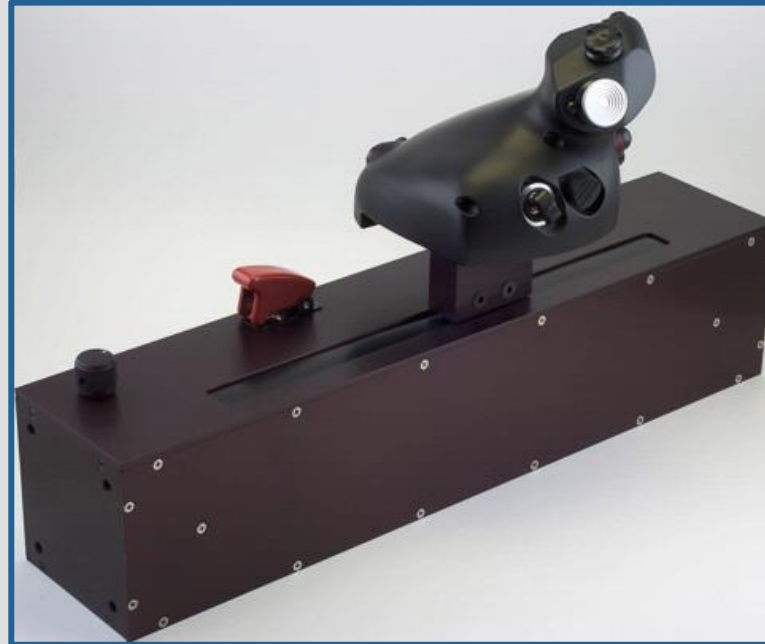


- ✦ Rudder Pedal System (RPS): Controls the rudders which change the yaw axis of the aircraft and also the wheel brakes
- ✦ Initially developed by a previous senior design team, we will incorporate this Rudder Pedal System with minor modification

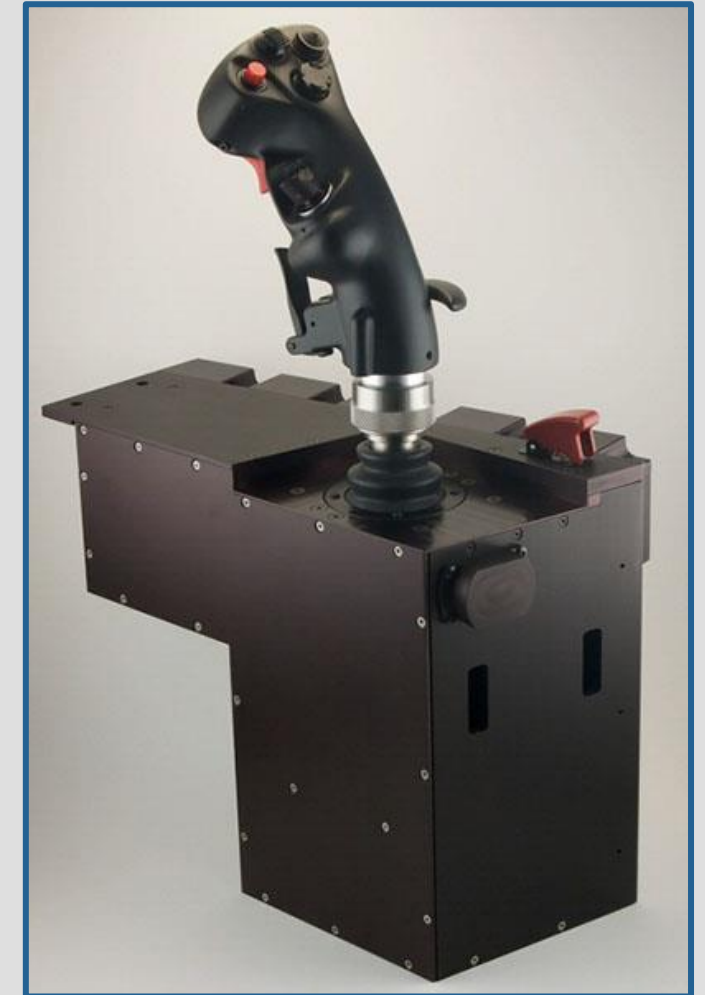
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HOTAS System

- ✈️ HOTAS: Hands on Throttle and Stick
- ✈️ Throttle: Controls the thrust from the jet engine
- ✈️ Stick: Controls the pitch and roll axes of the aircraft
- ✈️ Initially developed by a previous senior design team, we will modify to fit the needs of this project



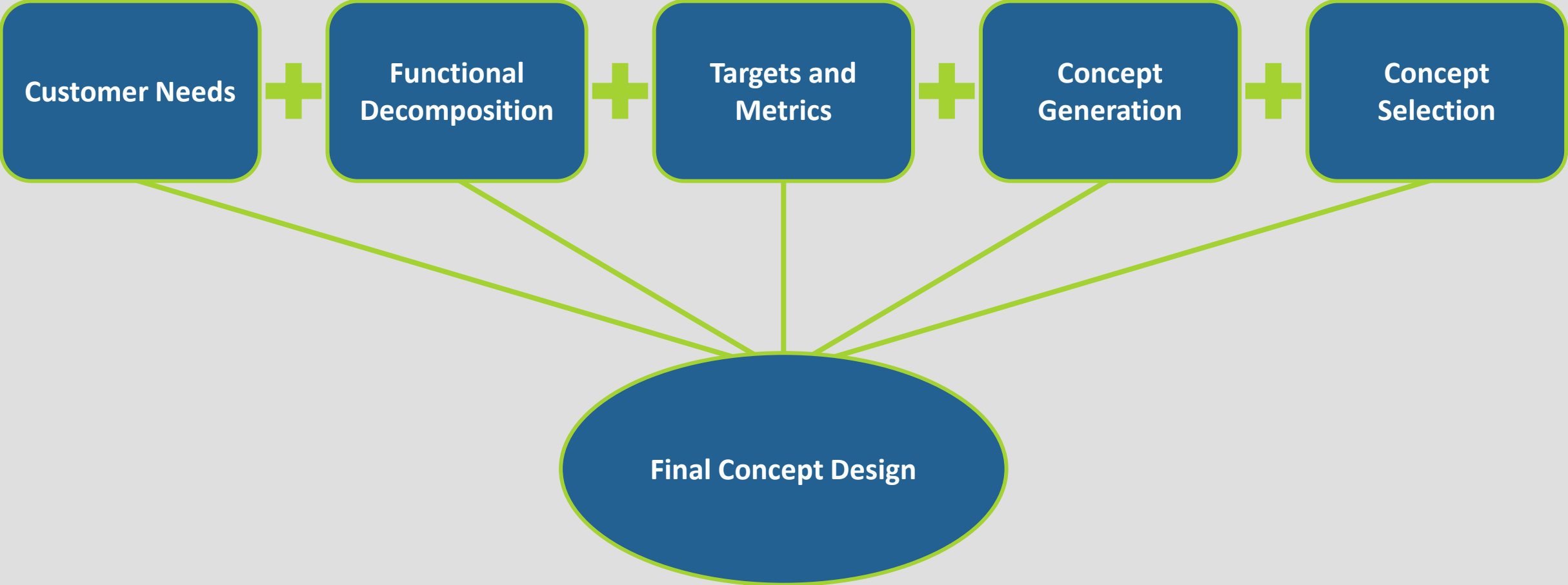
Throttle



Stick

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Last Semester

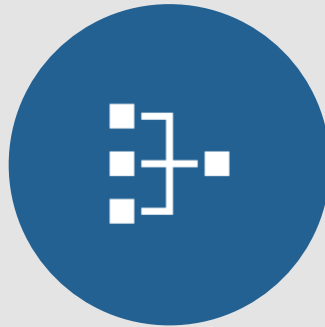


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Key Goals



Create finished,
working prototype



Integrate physical
sub-systems into the
simulation software



Keep
manufacturing
costs low



Design for use in
desktop or cockpit
training models

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Flight Control Functions

Pilot Interface

- ✈ Controls closely mimic F-35 look and feel
- ✈ Mechanic parts will withstand repeated use

Communicate to Software

- ✈ Controller position awareness
- ✈ Negligible input delay
- ✈ Inputs accurately affect simulated jet



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Critical Targets

Cost

Each new sub-system less than \$1000

Latency

No more than 20ms delay from input

Compatibility

3D printed cockpit and standard desk

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Additional Targets

Individual
Component < 35
pounds

Joystick deflection
13 degrees in all
directions

Throttle travel 6
inches

Operates 1 hour
without defect

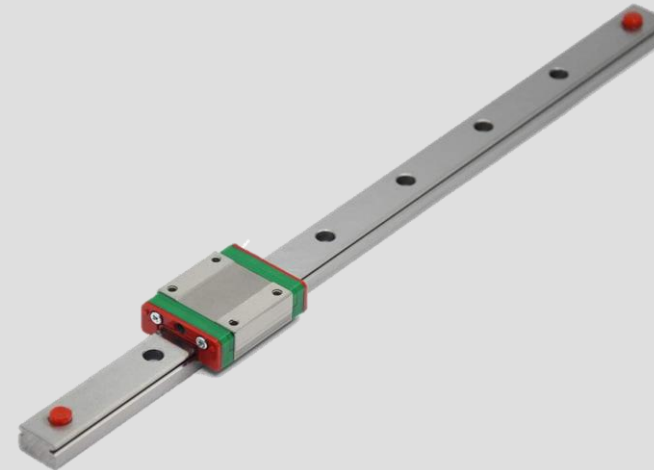
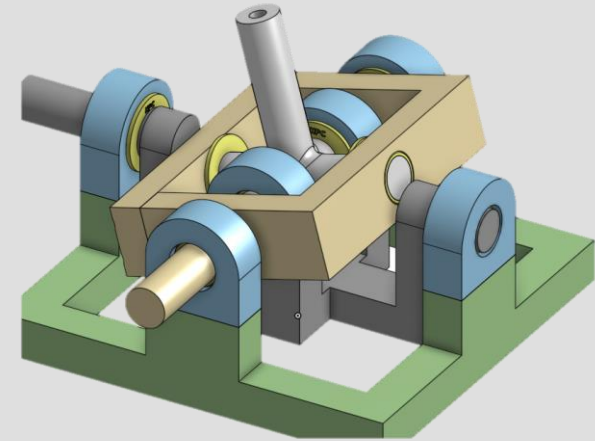
No more than 15
lbf required to
move RPS

HOTAS withstands
applied 7.5 lbf

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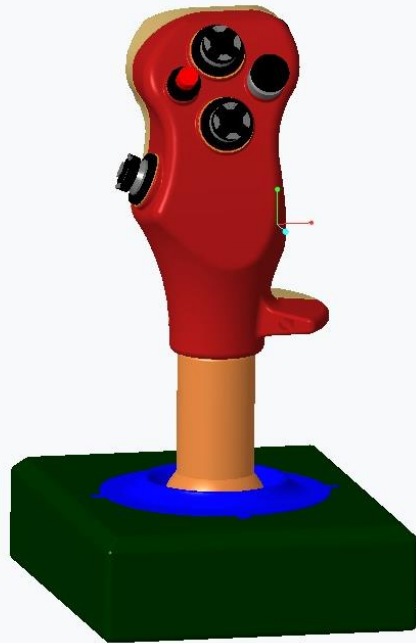
Final Design Selection

The design will feature potentiometer to sense position, individual microcontrollers for the RPS, throttle, and joystick, the throttle slides on a single rectangular rail, and the joystick is on a multiplane gimbal joint

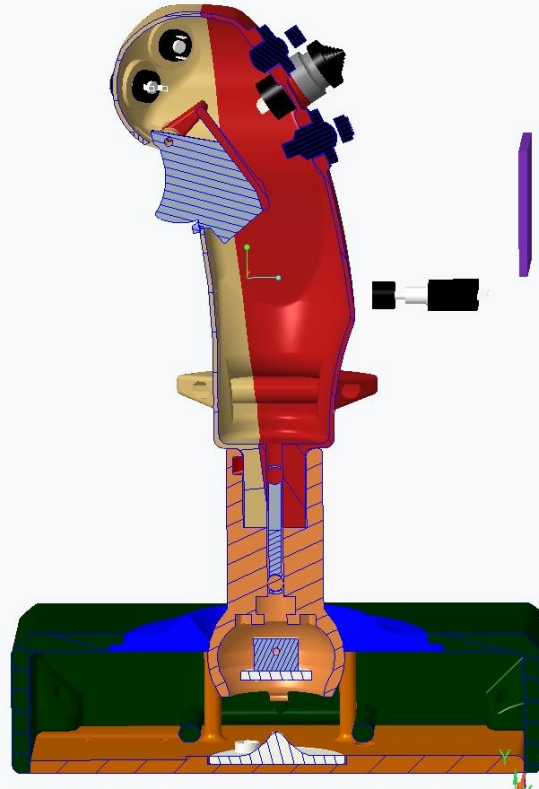


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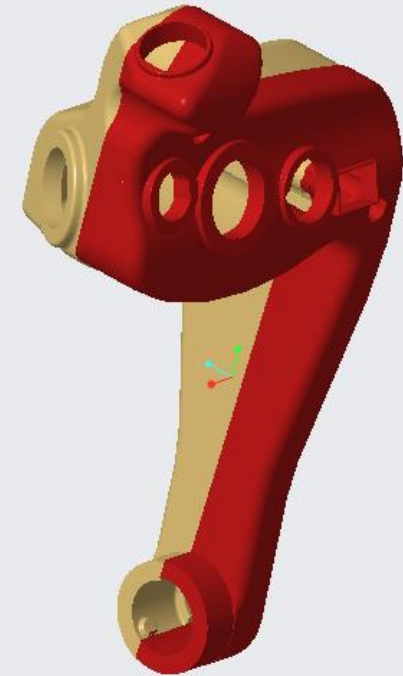
Current CAD Designs



Stick



Stick

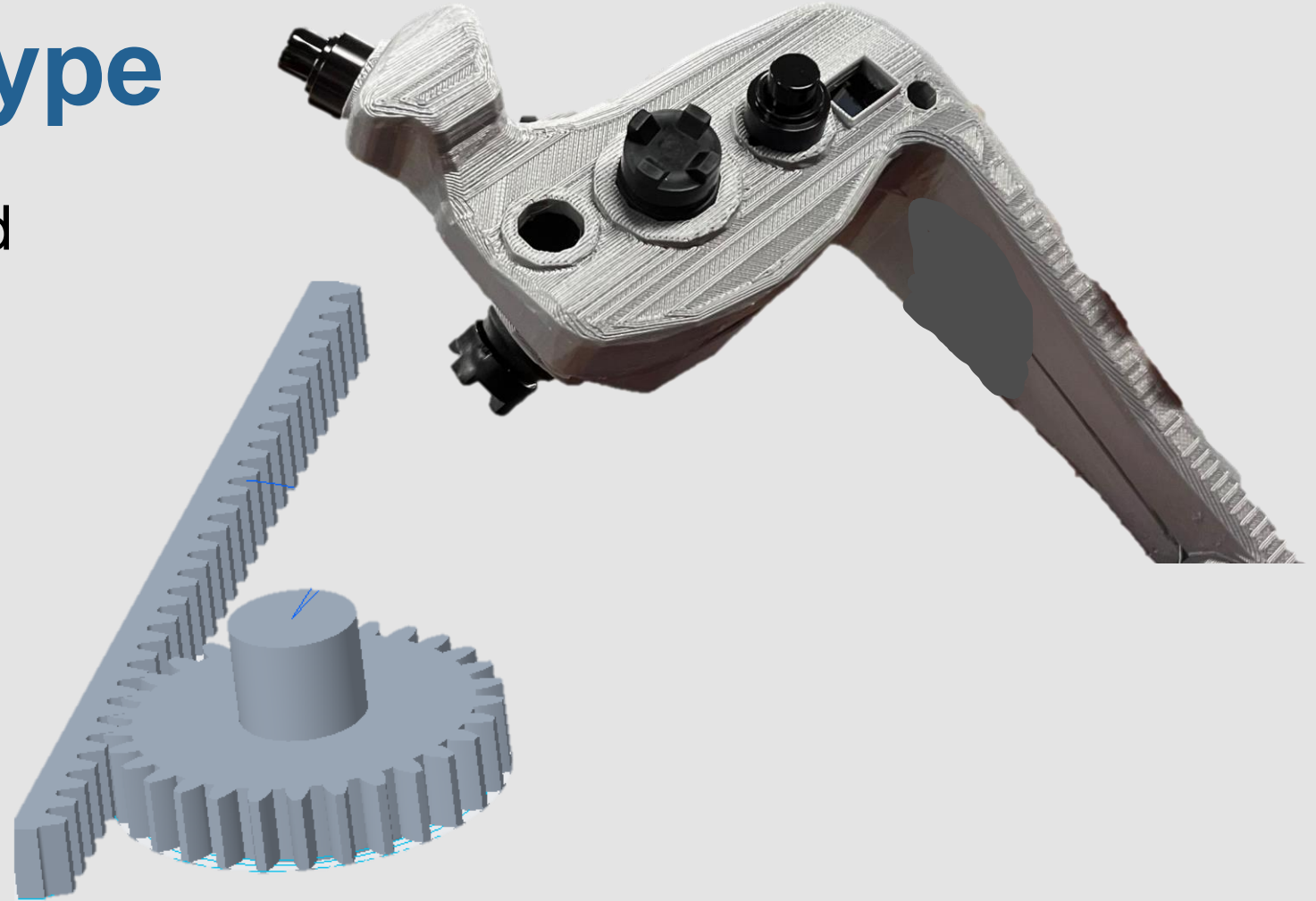


Throttle

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Throttle Prototype

- ✦ Need to adjust width and shape to be able to fit all required buttons
- ✦ The arm of the throttle needs to be moved to the center
- ✦ Figure out which printer will produce higher quality parts
- ✦ Size down the rack and pinion



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Software Update

Integration

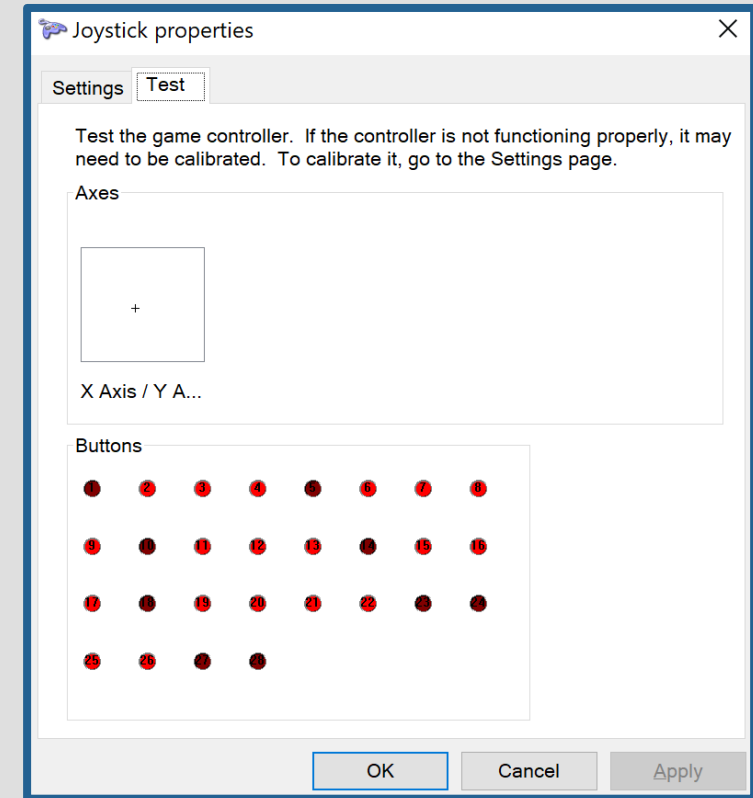
- ✦ Buttons are recognized by software
- ✦ Next function mapping

Firmware

- ✦ Over 90% complete

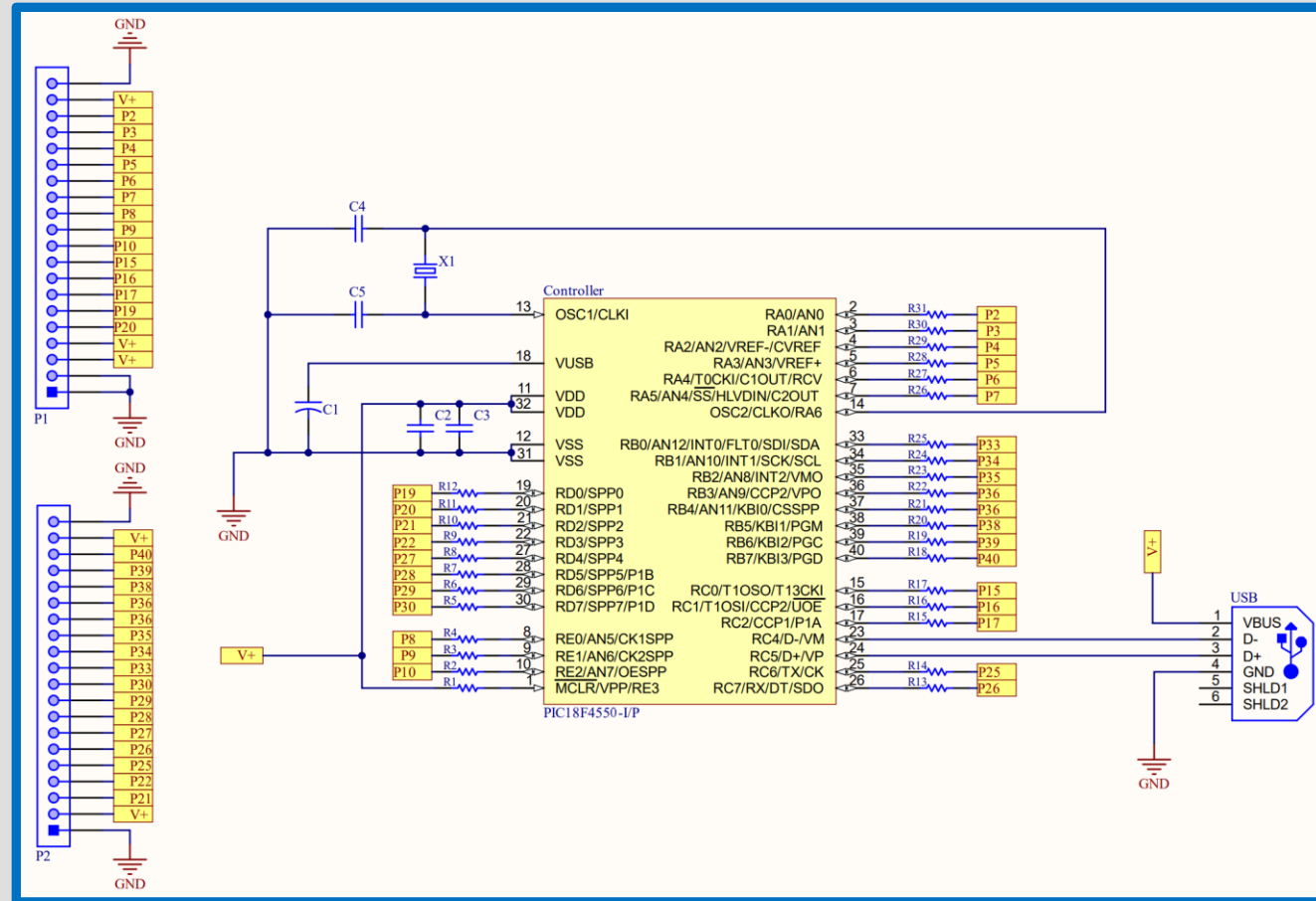
Latency

- ✦ Exceeds expectations
- ✦ Recognizes buttons immediately



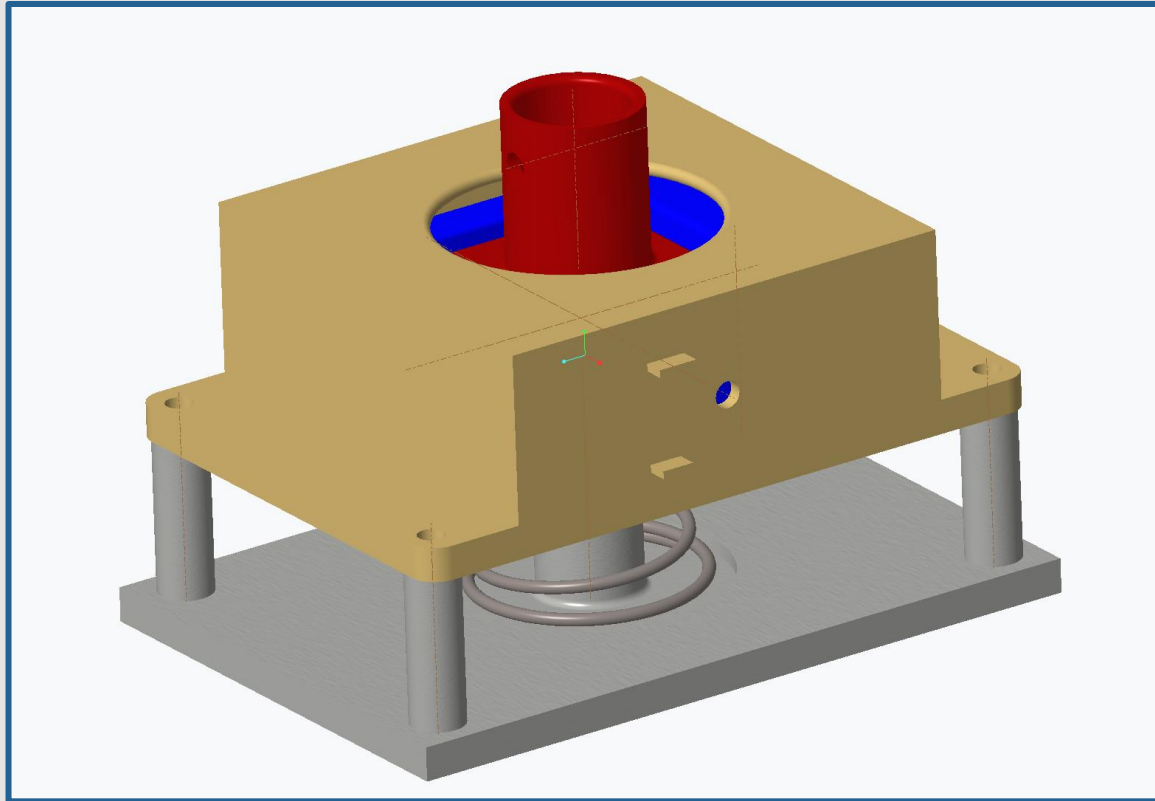
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Printed Circuit Board Schematic



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Update to Joystick Mechanism

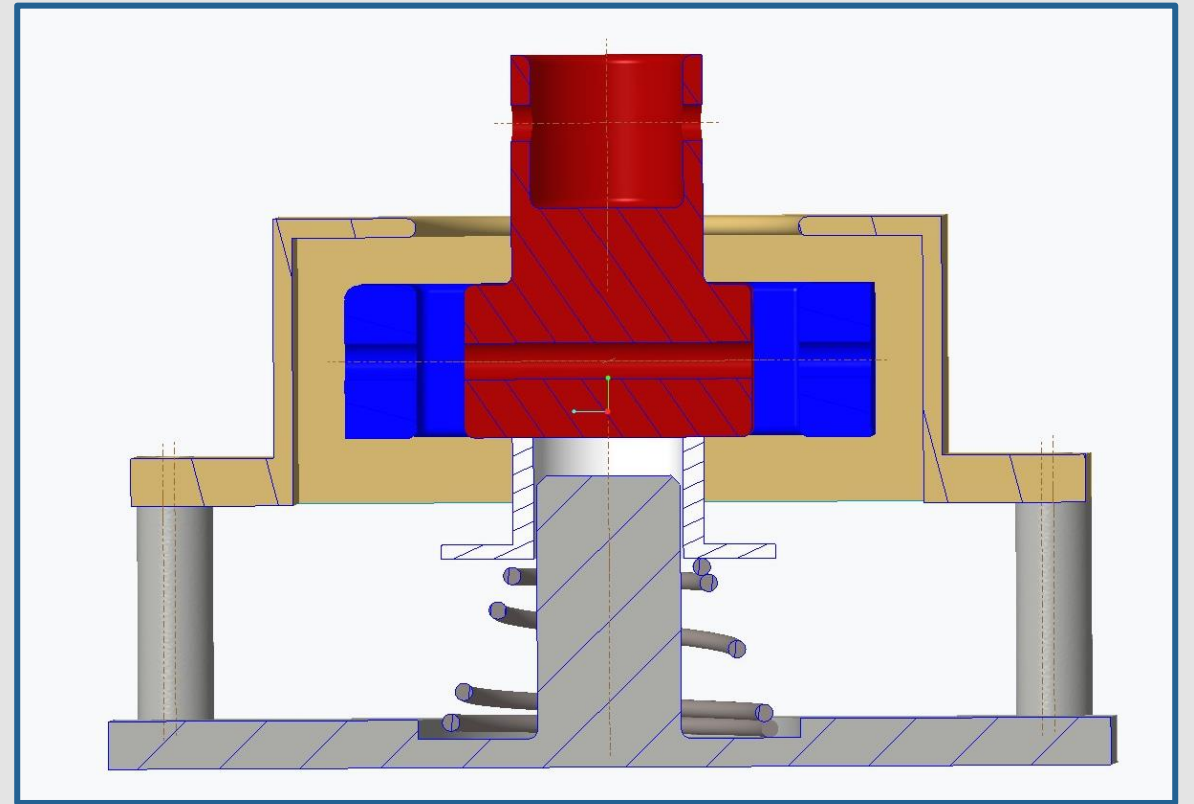


- ✦ The joystick mechanism has been changed.
- ✦ Retaining multiplane gimbal.
- ✦ Replacing linkages with multiple linear springs to “push plate” and single conical spring.

Emelia Rodriguez

Update to Joystick Mechanism

- ✦ Adjustment needed in geometry to meet targets.
- ✦ Next revision should include adjustable spring force.
- ✦ Conical and linear springs considerations:
 - ✦ Buckling behavior
 - ✦ Linearity of force per deflection (rate of a spring)



Emelia Rodriguez

Bill of Materials and Purchasing

- ✦ Several iterations of the bill of materials have been made since November
 - ✦ Since the original draft, a few parts have gone out of stock
- ✦ We have used about 45% of the budget on the first order
- ✦ Some items have already been purchased in order to get started on design and assembly.



Emelia Rodriguez

Current Priorities

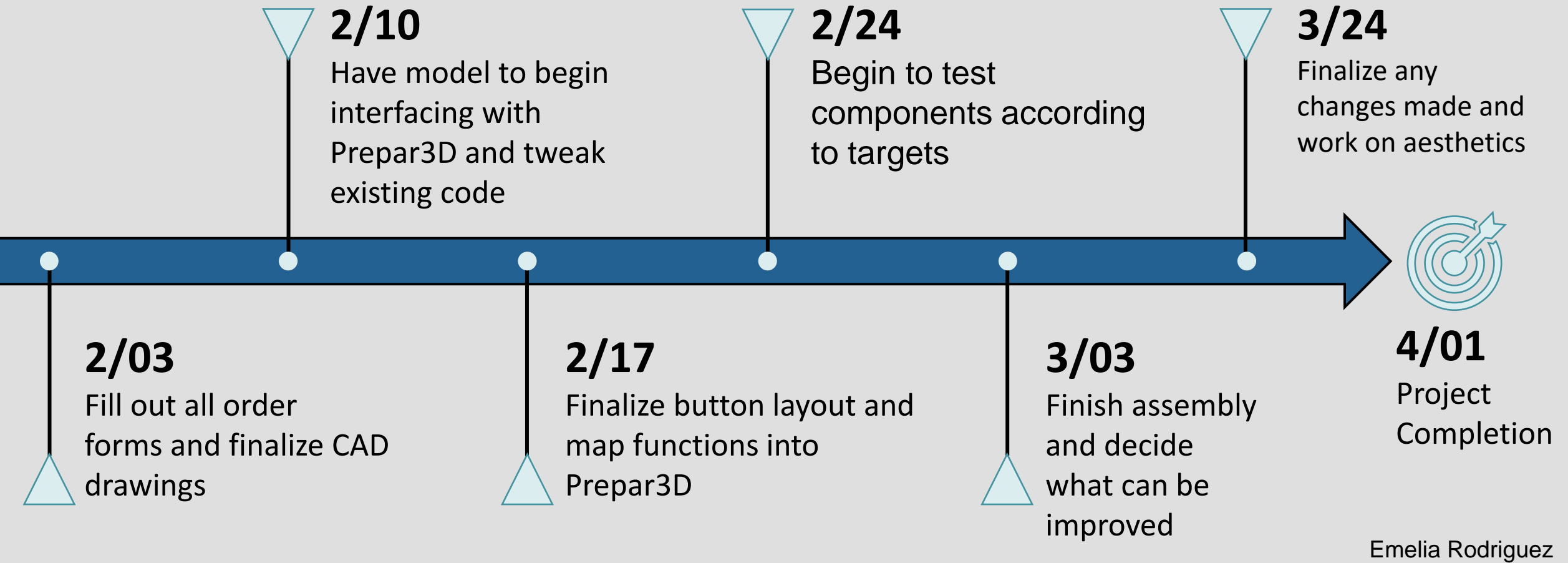
Complete 3D
printing of
prototypes

Submit
remaining
materials orders

Complete
design of PCB

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Project Timeline



Questions?



Design Team



Sponsor



Objective



Background



Functions



Targets



Current Work



Concept Selection



Future Work

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